



Mobile Robotics

Luc Jaulin

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Mobile Robotics presents the different tools and methods that enable the design of mobile robots; a discipline booming with the emergence of flying drones, underwater robots mine detectors, sailboats robots and robot vacuum cleaners.

Illustrated with simulations, exercises and examples, this book describes the fundamentals of modeling robots, developing the actuator concepts, sensor, control and guidance. Three-dimensional simulation tools are also explored, as well as the theoretical basis for reliable localization of robots within their environment.

- Illustrates simulation, corrected exercises and examples
- Explores different tools and methods to enable you to design mobile robots
- Features three-dimensional simulation tools as well as the theoretical explanation

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